It was noted in [1-3] that one of the deficiencies of the two-fluid model is the possibility of intersection of the particle trajectories and as a result an infinite mean density of particles at the intersection points. It was suggested in [2] that for flows with Kn << 1 there should be clusters of densely packed particles at the intersection points of the particle trajectories due to particle collisions. In the present paper we consider the case $\mathrm{Kn} \gg 1$. The ensemble of particles is described with the help of the collisionless kinetic equation. It is shown that in this model intersections of the particle trajectories are possible, and that the mean particle density remains finite everywhere. We study the stability of the flow of the mixture of gas and particles against small perturbations in the framework of our model. Unlike the two-fluid model [1, 2, 4] the perturbations are bounded and their amplitude is inversely proportional to the width of the velocity distribution function of the particles raised to a fractional power. The finite amplitude of the perturbations in [2] results from collisions in the particle "gas."

1. The kinetic equation for the particles in the collisionless limit can be found from the equations of [5]. Neglecting collisions and the diffusion of particles in velocity space (small $\mathrm{m}_{2}$ ), it has the form

$$
\begin{equation*}
\frac{\partial \mathscr{F}}{\partial t}+\mathbf{u}_{2} \frac{\partial \mathscr{F}}{\partial \mathbf{r}}+\left(\mathrm{g}-\frac{1}{\rho_{22}} \nabla p\right) \frac{\partial \mathscr{F}}{\partial \mathbf{u}_{2}}+\frac{\partial}{\partial \mathbf{u}_{2}}\left[\frac{\left(\mathbf{u}_{\mathbf{i}}-\mathbf{u}_{2}\right)}{\tau} \mathscr{F}\right]=0, \tag{1.1}
\end{equation*}
$$

where $u_{1}(t, r)$ and $p(t, r)$ are the velocity and pressure of the gas; $u_{2}$ and $\rho_{22}$ are the velocity and true density of the particles, $\mathscr{F}\left(t, r, u_{2}\right)$ is the single-particle distribution function of the particles, $g$ is the acceleration of gravity, $\tau$ is the relaxation time, and $\mathrm{m}_{2}$ is the volume concentration of particles.

The above simplifications occur when the following inequality is satisfied:

$$
\begin{equation*}
\mathrm{Kn} \simeq d / m_{2} L \gg 1 \tag{1.2}
\end{equation*}
$$

Here $d$ is the diameter of a particle and $L$ is the characteristic length of the variation of the mean flow parameters. Equations for the mean quantities are determined as in [5]

$$
\begin{equation*}
m_{2}=\int_{-\infty}^{+\infty} \mathscr{F} d \mathbf{u}_{2},\left\langle\mathbf{u}_{2}\right\rangle=\frac{1}{m_{2}} \int_{-\infty}^{+\infty} \mathbf{u}_{2} \mathscr{F} d \mathbf{u}_{2} \tag{1.3}
\end{equation*}
$$

Neglecting the effects of heat exchange between the gas and the particles, the system (1.1)(1.3) is closed by the equations for the gas phase obtained in [6]:

$$
\begin{gather*}
\frac{\partial \rho_{1}}{\partial t}+\frac{\partial}{\partial \mathbf{r}}\left(\rho_{1} \mathbf{u}_{1}\right)=0, \rho_{1}=\rho_{11} m_{1}, m_{1}+m_{2}=1  \tag{1.4}\\
\rho_{1} \frac{d_{1} \mathbf{u}_{1}}{d t}=\rho_{1} \mathbf{g}-m_{1} \nabla p-\rho_{2}\left(\frac{\mathbf{u}_{1}-\left\langle\mathbf{u}_{2}\right\rangle}{\tau}\right), \frac{d_{1}}{d t}=\frac{\partial}{\partial t}+\mathbf{u}_{1} \frac{\partial}{\partial \mathbf{r}}, \\
p=p\left(\rho_{11}\right), \rho_{22}=\text { const } ; \rho_{2}=\rho_{22} m_{2},
\end{gather*}
$$

where $\rho_{11}$ is the true density of the gas, $m_{1}$ is the volume concentration of the gas, and $\left\langle u_{2}\right\rangle$ is the average velocity of the particles.

Equation (1.1) is represented in the form

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$$
\begin{gathered}
D \mathscr{F} / D t=-\mathscr{F} \partial \mathbf{F}^{\prime} / \partial \mathbf{u}_{2} \\
D / D t=\partial / \partial t+\mathbf{u}_{2} \partial / \partial \mathrm{r}+\mathbf{F} \partial / \partial \mathbf{u}_{2}, \mathbf{F}^{\prime}=\left(\mathbf{u}_{1}-\mathbf{u}_{2}\right) / \tau
\end{gathered}
$$

and its general solution is written in the form

$$
\begin{gather*}
\mathscr{F}\left(t, \mathbf{r}, \mathbf{u}_{2}\right)=\mathscr{F}^{0}\left(t^{0}, \mathbf{r}^{*}, \mathbf{u}_{2}^{*}\right) \exp \left(-\int_{t^{0}}^{t} \frac{\partial \mathbf{F}^{\prime}}{\partial \mathbf{u}_{2}} d t\right),  \tag{1.5}\\
\mathbf{r}=\mathbf{r}\left(t, t^{0}, \mathbf{r}_{2}^{*}, \mathbf{u}_{2}^{*}\right), \mathbf{u}_{2}=\mathbf{u}_{2}\left(t, t^{0}, \mathbf{r}_{2}^{*}, \mathbf{u}_{2}^{*}\right) \\
\mathbf{u}_{2}^{*}=\left.\mathbf{u}_{2}\right|_{t=t^{0}}, \mathbf{r}_{2}^{*}=\left.\mathbf{r}_{2}\right|_{t=t_{0}} .
\end{gather*}
$$

Here the integral is taken along the characteristics determined by the second and third equations in (1.5), and $\mathscr{F}^{0}$ is an arbitrary function. Multiplying (1.1) by 1 and $u_{2}$, respectively, and integrating with respect to $u_{2}$ from $-\infty$ to $+\infty$, we find, in the special case where the particle trajectories do not intersect in the region of flow and random motion near the particles is absent at the initial instant of time, the solution of the system (1.1)-(1.4) reduces to the solution obtained with the two-fluid model.
2. We consider a one-dimensional problem on the decay of a discontinuity in the mixture of gas and solid particles in the region $D_{Z}\left\{-\infty<x_{2}<+\infty, t \geqq 0\right\}$. The volume concentration of particles $m_{2}$ will be assumed to be so small that it is possible to neglect the effect of the particles on the gas. Assuming $u_{1}=$ const, $p=$ const, $\rho_{11}=$ const, $g=0$, we transform the system (1.1)-(1.3) to the form

$$
\begin{align*}
& \frac{\partial \mathscr{F}}{\partial t}+u_{2} \frac{\partial \mathscr{F}}{\partial x_{2}}+\frac{\partial}{\partial u_{2}}\left(\frac{u_{1}-u_{2}}{\tau} \mathscr{F}\right)=0  \tag{2.1}\\
& m_{2}=\int_{-\infty}^{+\infty} \mathscr{F} d u_{2},\left\langle u_{2}\right\rangle=\frac{1}{m_{2}} \int_{-\infty}^{+\infty} u_{2} \mathscr{F} d u_{2}
\end{align*}
$$

For system (2.1) in the region $D_{z}$ we have the following initial conditions:

$$
\begin{gather*}
\mathscr{F}^{0}(t=0)=\frac{m_{2}^{0}}{\sqrt{2 \pi \sigma}} \exp \left(-\frac{\left(u_{2}-u_{2}^{0}\left(x_{2}\right)\right)^{2}}{2 \sigma}\right),  \tag{2.2}\\
u_{2}^{0}\left(x_{2}\right)=w^{s}-w^{\pi} \operatorname{arctg} \alpha x_{2}, \cdots \\
w^{s}=\left(w_{1}+w_{2}\right) / 2, w^{\pi}=\left(u_{1}-w_{2}\right) / \pi \\
w_{1}>w_{2}>u_{1}>0
\end{gather*}
$$

where $u_{2}{ }^{0}\left(x_{2}\right)$ is a "smeared" step function with width $\Delta x_{2} \sim 1 / \alpha$ and $u_{2}{ }^{0} \rightarrow w_{1}$ when $x_{2} \rightarrow-\infty$ and $u_{2}{ }^{0} \rightarrow w_{2}$ when $x_{2} \rightarrow+\infty$. The characteristics of Eq. (2.1) are determined from the equations

$$
\begin{equation*}
d x_{2} / d t=u_{2}, d u_{2} / d t=\left(u_{1}-u_{2}\right) / \tau \tag{2.3}
\end{equation*}
$$

Introducing the notation $u_{2} *=u_{2}(t=0), x_{2} *=x_{2}(t=0)$, we obtain from (2.3)

$$
\begin{gathered}
u_{2}=u_{1}+\left(u_{2}^{*}-u_{1}\right) \mathrm{e}^{-t / \tau} \\
x_{2}=x_{2}^{*}+u_{1} t+\left(u_{2}^{*}-u_{1}\right) K, K=\tau\left(1-\mathrm{e}^{-t / \tau}\right)
\end{gathered}
$$

Substituting (2.2) in (1.5) and introducing a change of variables

$$
d u_{2}=\frac{\partial u_{2}}{\partial u_{2}^{*}} d u_{2}^{*}=\mathrm{e}^{-t / \tau} d u_{2}^{*}
$$

we find

$$
\begin{equation*}
m_{2}=\frac{m_{2}^{0}}{\sqrt{2 \pi \sigma}} \int_{-\infty}^{+\infty} \exp \left(-\frac{\left(u_{2}^{*}-u_{2}^{0}\left(x_{2}^{*}\right)\right)^{2}}{2 \sigma}\right) d u_{2}^{*} \tag{2.4}
\end{equation*}
$$

The integral (2.4) is evaluated by the saddle-point method for fixed values of $t$ and $x_{2}$.

The function $\varphi\left(u_{2}{ }^{*}, t, x_{2}\right)=\left(u_{2} *-w^{s}+w^{\pi} \arctan \alpha x_{2}\right)^{2}$ is expanded in a Taylor series up to terms of order $\left(y-u_{2} *\right)^{2}$, where $y$ and $x_{2} *$ are determined from the system of equations

$$
\begin{equation*}
y-w^{s}+w^{\pi} \operatorname{arctg} \alpha x_{2}^{*}=0, x_{2}^{*}+u_{1} t+\left(y-u_{1}\right) K-x_{2}=0 \tag{2.5}
\end{equation*}
$$

Substituting (2.5) into (2.4) we have

$$
\begin{equation*}
\left.m_{2}=\sum_{l=1}^{n} m_{2}^{0}| | 1-\frac{w^{\pi} \alpha K}{1+\left(\alpha x_{2}^{*}\right)^{2}} \right\rvert\,, x_{2}=x_{2}^{*}+u_{1}(t-K)+u_{2}^{0}\left(x_{2}^{*}\right) K \tag{2.6}
\end{equation*}
$$

Here $t$ and $x_{2}$ are fixed and $n$ is the number of roots of the second equation of (2.6), which is solved graphically (Fig. 1), where $Y=w^{\pi} \arctan \alpha x_{2} *-w^{s}, X=\left(x_{2}^{*}-x_{2}+u_{1}(t-K)\right) / K$. The root is given by the intersection point of the straight line $X$ and the curve $Y$, i.e., ( $\mathrm{Y}=\mathrm{X}$ ). It follows from the results shown in Fig. 1 that in the region bounded by the lines passing through the points $\left(\nu^{-}, \xi^{+}\right)$and $\left(\nu^{+}, \xi^{-}\right)$, the number of roots is $n=3$ and elsewhere $n=1$. Differentiating the second equation of (2.6), we obtain

$$
\begin{gather*}
\left(\frac{\partial x_{2}}{\partial x_{2}^{*}}\right)_{t}=1-\frac{\alpha w^{\pi} K}{1+\left(\alpha x_{2}^{*}\right)^{2}}, \text { hence }  \tag{2.7}\\
\frac{\partial x_{2}}{\partial x_{2}^{*}}>0, \quad-\infty<x_{2}^{*}<\xi^{-}(t) \\
\frac{\partial x_{2}}{\partial x_{2}^{*}}<0, \quad \xi^{-}(t)<x_{2}^{*}<\xi^{+}(t) \\
\frac{\partial x_{2}}{\partial x_{2}^{*}}>0, \quad \xi^{+}(t)<x_{2}^{*}<+\infty \\
\frac{\partial x_{2}}{\partial x_{2}^{*}}=0, \quad x_{2}^{*}=\xi^{+}(t), x_{2}^{*}=\xi^{-}(t)
\end{gather*}
$$

where $\xi^{ \pm}(t)= \pm \frac{1}{\alpha} \sqrt{\alpha w^{\pi} K-1} ; \alpha w^{\pi} K \geqslant 1$.
Thus the trajectories in the ( $t, \mathrm{x}_{2}$ ) plane will have the form shown in Fig. 2. The curve $\Gamma_{1}$ is the caustic and is defined by the equations

$$
\begin{gathered}
x_{2}=u_{1}(t-K)+w^{s} K \pm\left(\frac{1}{\alpha} \sqrt{w^{\pi} \alpha K-1}-w^{\pi} K \operatorname{arctg} \sqrt{w^{\pi} \alpha K-1}\right) \\
t^{+}=-\tau \ln \left(1-1 / \alpha w^{\pi} \tau\right), x_{2}^{+}=u_{1} t^{+}+1 /\left(w^{\pi} \alpha\right)\left(w^{s}-u_{1}\right)
\end{gathered}
$$

On the caustic we have the condition $\partial x_{2} / \partial x_{2} *=0$ [7]; therefore, in view of (2.6) and (2.7) the quantity $m_{2}$ goes to infinity on $\Gamma_{1}$. The solution on the caustic can be found if we expand $\varphi$ to order $\left(y-u_{2} *\right)^{4}$ [the coefficient in front of $\left(y-u_{2} *\right)^{2}$ is zero on $\left.\Gamma_{1}\right]$. Substituting this expansion into (2.4), we obtain the following result on $\Gamma_{1}$ :

$$
\begin{equation*}
m_{2} \approx \frac{m_{2}^{0}}{\sqrt{\pi} \sigma^{1 / 4}} \frac{\Gamma\left(\frac{1}{4}\right)}{2^{1 / 4}} \frac{\left(\alpha x_{2}^{*}\right)^{2}+1}{\left(\alpha^{3} w^{\pi} K^{2} x_{2}^{*}\right)^{1 / 2}}, x_{2}^{*}=\xi^{+}(t) \tag{2.8}
\end{equation*}
$$

Here $\Gamma$ is the gamma function and $\sigma /\left(w^{\pi}\right)^{2} \ll 1$ (from the convergence condition on the series). The solution is valid everywhere on $\Gamma_{1}$ except at the point ( $t^{+}, \mathrm{x}_{2}^{+}$) where $\mathrm{m}_{2} \rightarrow \infty$. Similarly, keeping terms of order $\left(y-u_{2} *\right)^{6}$ in the expansion of $\varphi$, we find the solution at the point $\left(t^{+}, x_{2}^{+}\right)$

$$
\begin{equation*}
m_{2}^{+} \approx \frac{m_{2}^{0}}{\sqrt{2 \pi} \sigma^{1 / 3}} \frac{\Gamma\left(\frac{1}{6}\right)(18)^{1 / 6}}{3} \frac{1}{\left(\alpha^{3} w^{\pi} K^{3}\right)^{1 / 3}}, \alpha w^{\pi} K=1 \tag{2.9}
\end{equation*}
$$

The applicability condition for this solution [using (2.9) and $\mathrm{Kn} \gg 1$ ] has the form

$$
m_{2}^{+} \ll 1, \alpha d / m_{2}^{+} \gg 1
$$



Fig. 1


Fig. 2


Fig. 3

The solution of the problem considered here with the initial condition $u_{2}=u_{2}{ }^{0}\left(x_{2}\right)$, $m_{2}=m_{2}{ }^{0}$ generally cannot be obtained in the two-fluid model [6] because inside $r_{1}$ three particle trajectories pass through each point. If we introduce two additional phases associated with the particles, then a solution of the type (2.6) can be obtained everywhere except on $\Gamma_{1}$ where $m_{2}$ goes to infinity. When the ensemble of particles is modeled as a continuous medium, only one value of the velocity is defined at each point (for a fixed phase) and, therefore, $c=0$ and it then follows from (2.8) and (2.9) that $m_{2} \rightarrow \infty$ on $\Gamma_{1}$. We conclude that this infinity is irremovable in the framework of a collisionless continuous medium model. The singularity in $m_{2}$ can be removed by introducing collisions into the particle phase for $\mathrm{Kn} \ll 1$ [2] or by using the kinetic equation (1.1) for $\mathrm{Kn} \gg 1$, where $\mathrm{Kn} \cong \mathrm{d} /\left(\mathrm{m}_{2} \mathrm{~L}\right)$ is the Knudsen number. Using the inequality $\sigma /\left(w^{\pi}\right)^{2} \ll 1, \alpha w^{\pi} \mathrm{K} \sim 1$ and the solution (2.6)-(2.9), it is easy to show that the maximum value of $m_{2}$ is attained on the caustic and hence a cluster of particles forms on the caustic. The formation of the cluster results from singularities in the behavior of the particle trajectories rather than from collisions between particles, as in $[2,3]$.

When the width $\Delta x_{2} \sim I / \alpha$ goes to zero $(\alpha \rightarrow \infty)$ and $u_{2}{ }^{0}\left(x_{2}\right)$ transforms into a step function, it follows from (2.6) that the solution has the form

$$
\begin{gathered}
m_{2}=\sum_{l=1}^{n} m_{2}^{0} \\
x_{2}=x_{2}^{*}+u_{1}(t-K)+u_{2}^{0}\left(x_{2}^{*}\right) K, u_{2}^{0}\left(x_{2}^{*}\right)=w^{s}-\left(\frac{2}{\pi}\right)^{-1} w^{\pi} \theta\left(x_{2}^{*}\right) \\
\theta\left(x_{2}^{*}\right)=\left\{\begin{array}{cc}
-1, & x_{2}^{*}<0 \\
1, & x_{2}^{*}>0
\end{array}\right.
\end{gathered}
$$

The function $Y=-u_{2}{ }^{0}\left(x_{2} *\right)$ is shown in Fig. 1 by dashed curves and in the region bounded by the straight lines 1 and 2 there are two roots of $Y=X(n=2)$ and one root ( $n=1$ ) elsewhere. The corresponding pattern of trajectories is shown in Fig. 3, where the positions of the curves $\Gamma_{2}$ are determined by the equations

$$
x_{2}=u_{1}(t-K)+w_{2} K, x_{2}=u_{1}(t-K)+w_{1} K
$$

In the region bounded by the curves $\Gamma_{2}$ we have $m_{2}=2 m_{2}{ }^{0}$, and elsewhere $m_{2}=m_{2}{ }^{0}$.
We study the stability of the stationary solution of the system (1.2)-(1.5) to small perturbations. In the one-dimensional case, neglecting the volume occupied by the particles (small $\mathrm{m}_{2}$ ), the system (1.1)-(1.5) can be written in the form

$$
\begin{gather*}
\frac{\partial \mathscr{F}}{\partial t}+u_{2} \frac{\partial \mathscr{F}}{\partial x}+\frac{\partial}{\partial u_{2}} F \mathscr{F}=0, F=\frac{u_{1}-u_{2}}{\tau}-g_{\eta}  \tag{3.1}\\
m_{2}=\int_{-\infty}^{+\infty} \mathscr{F} d u_{2},\left\langle u_{2}\right\rangle=\frac{1}{m_{2}} \int_{-\infty}^{+\infty} u_{2} \mathscr{F} d u_{2}, \rho_{22}=\mathrm{const} \\
\frac{\partial u_{i}}{\partial t}+u_{1} \frac{\partial u_{i}}{\partial x}=-\frac{1}{\rho_{11}} \frac{\partial p}{\partial x}-\frac{m_{2} \rho_{22}}{\rho_{11}} \frac{u_{1}-\left\langle u_{2}\right\rangle}{\tau}-g \\
\frac{\partial \rho_{1 i}}{\partial t}+\frac{\partial}{\partial x}\left(\rho_{11} u_{1}\right)=0, p=p\left(\rho_{11}\right), \tau=\frac{\rho_{22} d^{2}}{18 \mu}
\end{gather*}
$$

The stationary solution of the system of equations (3.1), neglecting the compressibility of the gas, is

$$
\begin{gather*}
f^{0}=\left(\rho_{11}^{0} ; m_{2}^{0} ; u_{1}^{0} ;\left\langle u_{2}\right\rangle^{0}\right)=\text { const },  \tag{3.2}\\
\frac{u_{1}^{0}-a}{\tau}=g, \frac{d p^{0}}{d x}=-g\left(\rho_{11}^{0}+\rho_{2}^{0}\right), a=\left\langle u_{2}\right\rangle^{0}
\end{gather*}
$$

At the instant $t=0$ a perturbation of the stationary solution is turned on:

$$
f=f^{0}(x)+f^{\prime}(x), f^{\prime}(x)=\delta f \sin k x, \delta f \ll f^{0}
$$

Since short-wavelength perturbations are of the most interest, we consider the case of large $k$ satisfying the inequality $k \tau c_{0} \gg 1$, and for long-wavelength perturbations we obtain the inequality

$$
\begin{equation*}
\dot{d} \ll \lambda \ll\left(\rho_{22} / \rho_{11}\right) d \tag{3.3}
\end{equation*}
$$

where $\lambda=2 \pi / k$ and $c_{0}$ is the speed of sound in the gas. It follows from (3.1) that the equations for the gas phase are nonlinear and therefore we represent the solution vector for the gas phase as a sum

$$
\begin{equation*}
\varphi^{*}=\varphi^{0}(x)+\varphi^{\prime}(x, t)\left(\varphi^{0}(x)=\left(p^{0}(x), u_{1}^{0}(x), \rho_{11}^{0}\right), \varphi^{\prime} / \varphi^{0} \ll 1\right) \tag{3.4}
\end{equation*}
$$

and linearize the equations for the gas about the stationary solution (3.2). Taking into account (3.2)-(3.4), we obtain from the system (3.1) the following equations, all to order $\mathrm{O}\left(1 / \mathrm{k} \tau \mathrm{C}_{0}\right)$ :

$$
\begin{gather*}
\frac{\partial \mathscr{F}}{\partial t}+u_{2} \frac{\partial \mathscr{F}}{\partial x}+\frac{\partial}{\partial u_{2}} F \mathscr{F}=0, F=\left(a-u_{2}+u_{1}^{\prime}\right) / \tau_{;} \\
m_{2}=\int_{-\infty}^{+\infty} \mathscr{F} d u_{2},\left\langle u_{2}\right\rangle=\frac{1}{m_{2}} \int_{-\infty}^{+\infty} u_{2} \mathscr{F} d u_{2}, u_{2}=a+u_{2}^{\prime}  \tag{3.5}\\
\frac{d u_{2}^{\prime}}{d t}=\frac{u_{1}^{\prime \prime}-u_{2}^{\prime}}{\tau}, \frac{d x_{2}}{d t}=a+u_{2}^{\prime}, \dot{a}=\text { const } \\
\frac{\partial u_{1}^{\prime}}{\partial t}+u_{1}^{0} \frac{\partial u_{1}^{\prime}}{\partial x}+\frac{1}{\rho_{11}^{0}} \frac{\partial p^{\prime}}{\partial x}=0, p^{\prime}=\rho_{11}^{\prime} c_{0}^{2} \\
\frac{\partial}{\partial t}\left(\frac{\rho_{11}^{\prime}}{\rho_{11}^{0}}\right)+u_{1}^{0} \frac{\partial}{\partial x}\left(\frac{\rho_{11}^{\prime}}{\rho_{11}^{0}}\right)+\frac{\partial u_{1}^{\prime}}{\partial x}=0
\end{gather*}
$$

We note that the last three equations of (3.5) describe the propagation of the perturbations in the gas and do not depend on the parameters of the second phase. This means that we can study the equations for the particles without assuming that the perturbations are small, whereas for the gas phase it is sufficient to consider the linearized equations for the perturbations. We note that $u_{2}$ ' is not the perturbation of $u_{2}$, but the difference of $u_{2}$ from $a \equiv\left\langle u_{2}\right\rangle^{0}$ 。

The initial conditions for the system (3.5) are written in the form

$$
\begin{gather*}
\left.\varphi^{\prime}\right|_{t=0}=\delta \varphi \sin k x  \tag{3.6}\\
\left.\mathscr{F}\right|_{t=0}=\frac{m_{2}^{\alpha}}{\sqrt{2 \pi \sigma}} \exp \left(-\frac{\left(u_{2}-\left(a+\delta u_{2} \sin k x\right)\right)^{2}}{2 \sigma}\right) \\
m_{2}^{\alpha}=m_{2}^{\mathbf{0}}+\delta m_{2} \sin k x
\end{gather*}
$$

where $\varphi^{0}$ is defined in (3.4). Rewriting the last three equations of (3.5) in characteristic form, we have, with the help of (3.6),

$$
\begin{align*}
u_{1}^{\prime} & =\frac{1}{2}\left(\delta r \sin k\left(x-\left(u_{1}^{0}+c_{0}\right) t\right)+\delta s \sin k\left(x-\left(u_{1}^{0}-c_{0}\right) t\right)\right)  \tag{3.7}\\
\frac{\rho_{11}^{\prime}}{\rho_{11}^{0}} & =\frac{1}{2 c_{0}}\left(\delta r \sin k\left(x-\left(u_{1}^{0}+c_{0}\right) t\right)-\delta s \sin k\left(x-\left(u_{1}^{0}-c_{0}\right) t\right)\right)
\end{align*}
$$

$$
\begin{equation*}
\delta r=\delta u_{1}+c_{0} \frac{\delta \rho_{11}}{\rho_{11}^{0}}, \delta s=\delta u_{1}-c_{0} \frac{\delta \rho_{11}}{\rho_{11}^{0}} . \tag{3.7}
\end{equation*}
$$

Integrating the equation of motion of a particle, we find

$$
\begin{gather*}
u_{2}^{\prime}=u_{2}^{\prime *} \mathrm{e}^{-t / \tau}+\mathrm{e}^{-t / \tau}\left(\int_{0}^{t} \frac{u_{1}^{\prime}\left(t^{\prime}, x_{2}\left(t^{\prime}\right)\right)}{\tau} \mathrm{e}^{t^{\prime} / \tau} d t^{\prime}\right),  \tag{3.8}\\
x_{2}=x_{2}^{*}+a t+u_{2}^{\prime *} K(t)+\int_{0}^{t} d t^{\prime} \mathrm{e}^{-t^{\prime} / \tau} \int_{0}^{t^{\prime}} \frac{u_{1}^{\prime}\left(t^{\prime \prime}, x_{2}\left(t^{\prime \prime}\right)\right)}{\tau} \mathrm{e}^{t^{\prime \prime} / \tau} d t^{\prime \prime},
\end{gather*}
$$

where $K(t)=\tau\left(1-e^{-t / \tau}\right) ; u_{1}^{\prime}\left(t^{\prime \prime}, x\right)$ is determined by (3.7). The solution of the second equation of (3.8) is found by iteration. We choose as the zeroth approximation

$$
\begin{equation*}
x_{2}^{(0)}=x_{2}^{*}+a t+u_{2}^{\prime *} K(t) \tag{3.9}
\end{equation*}
$$

Substituting $x_{2}(0)$ into the first equation of (3.8) and the result into the second equation, we compute $x_{2}(1)$, then $x_{2}(2)$, and so on, by repeating this procedure. Assuming that $x_{2}(n)=x_{2} *+a t+\varepsilon K$, in order to calculate $x_{2}(n+1)$ we must evaluate an integral of the form

$$
I=\int_{0}^{t} d t^{\prime} \mathrm{e}^{-t^{\prime} / \tau} \int_{0}^{t^{\prime}} \frac{\mathrm{e}^{t^{\prime \prime} \tau}}{\tau}\left[\frac{\delta s}{2} \sin \left(k b^{-} t^{\prime \prime}+k \varepsilon K\left(t^{\prime \prime}\right)+\alpha\right)-\frac{\delta r}{2} \sin \left(k b^{+} t^{\prime \prime}-k \varepsilon \dot{K}\left(t^{\prime \prime}\right)-\alpha\right)\right] d t^{\prime \prime}
$$

where $b^{-}=c_{0}-\left(u_{1}^{0}-a\right) ; ~ a=k x_{2}{ }^{*} ; \mathrm{kb}^{-} \tau \gg 1$ (large $k$ ); $b^{+}=c_{0}+\left(u_{1}{ }^{0}-\alpha\right) ; k b^{+} \tau \gg 1$; $\mathrm{b}^{-}>0$ (subsonic with respect to the flow velocity). Using the properties of integrals of rapidly oscillating functions [8], we have

$$
\begin{equation*}
I=(A-\varepsilon B) K \cos \alpha+O\left(1 /\left(\omega^{+}\right)^{2}+1 /\left(\omega^{-}\right)^{2}\right) \tag{3.10}
\end{equation*}
$$

where $\omega^{-}=k b^{-} \tau ; \omega^{+}=k b^{+} \tau$;

$$
A=\frac{\delta s}{2 \omega^{-}}-\frac{\delta r}{2 \omega^{+}} ; B=\frac{\delta s}{\left(2 \omega^{-} b^{-}\right)}+\frac{\delta r}{\left(2 \omega^{+} b^{+}\right)}
$$

Taking into account (3.8) and (3.10), we obtain the $n-t h$ iteration

$$
\begin{equation*}
x_{2}^{(n)}=x_{2}^{(0)}+K\left(\frac{A}{B} \sum_{k=1}^{n}(-1)^{(k-1)} \Delta^{k}+u_{2}^{\prime *} \sum_{k=1}^{n}(-1)^{k} \Delta^{k}\right) \tag{3.11}
\end{equation*}
$$

where $\Delta=B \cos k x_{2} *$. Using mathematical induction, it is a simple matter to prove that (3.11) is the correct solution and the sequence $x_{2}{ }^{(0)}, x_{2}(1), \ldots, x_{2}{ }^{(n)}$ is a geometric progression with a sum equal to

$$
\begin{equation*}
x_{2}=x_{2}^{(0)}+K\left(\frac{A}{B}-u_{2}^{\prime *}\right) \frac{\Delta}{1+\Delta} \tag{3.12}
\end{equation*}
$$

Because the integral (3.10) was calculated to within an accuracy of $0\left(1 /\left(\omega^{+}\right)^{2}+1 /\left(\omega^{-}\right)^{2}\right)$, the final expression for $x_{2}$, to the same accuracy, can be written [with the help of (3.12)] in the form

$$
\begin{equation*}
x_{2}=x_{2}^{*}+a t+u_{2}^{\prime *} K+\left(\frac{\delta s}{2 \omega^{-}}-\frac{\delta r}{2 \omega^{+}}\right) K \cos k x_{2}^{*}-\left(\frac{\delta s}{2 \omega^{-} b^{-}}+\frac{\delta r}{2 \omega^{+} b^{+}}\right) u_{2}^{\prime *} K \cos k x_{2}^{*} \tag{3.13}
\end{equation*}
$$

Equation (3.13) can be obtained from (3.11) if we put $n=1$, i.e., when it is sufficient to use a single iteration.

Substituting (3.7) and (3.13) into the first equation of (3.8), we have

$$
\begin{equation*}
u_{2}^{\prime}=u_{2}^{\prime *} \mathrm{e}^{-t / \tau}+\mathrm{e}^{-t / \tau}\left(\frac{\delta s}{2} I_{1}-\frac{\delta r}{2} I_{2}\right)+O\left((\delta w)^{2}, \frac{u_{2}^{\prime}}{c_{0}} \delta w\right) \tag{3.14}
\end{equation*}
$$



Fig. 4

$$
\begin{gather*}
I_{1,2}=\frac{1}{\omega^{ \pm}}\left[\left(1 \pm \frac{u_{2}^{\prime *}}{b^{ \pm}}\right) \cos k x_{2}^{*}-\left(\mathrm{e}^{ \pm / \tau} \pm \frac{u_{2}^{* *}}{b^{ \pm}}\right) \cos \left(\omega^{ \pm} \varphi^{ \pm}-k x_{2}^{*}\right)\right]+O\left(1 / \omega^{ \pm}\right)^{2}  \tag{3.14}\\
\varphi^{ \pm}=t / \tau \mp \frac{u_{2}^{\prime *}}{b^{ \pm} \tau} K \mp \frac{\delta \tilde{u}_{1}}{b^{ \pm} \tau} K, \delta \tilde{u}_{i}=\delta u_{1} \cos k x_{2}^{*}
\end{gather*}
$$

and from this result we can compute the partial derivatives $\left(\frac{\partial x_{2}^{*}}{\partial u_{2}^{\prime *}}\right),\left(\frac{\partial u_{2}^{\prime}}{\partial u_{2}^{\prime *}}\right)$ at fixed $t$ and $x_{2}$
in the form in the form

$$
\begin{gather*}
\frac{\partial x_{2}^{*}}{\partial u_{2}^{\prime *}}=-K /\left(1-\delta w \frac{K}{\tau} \sin k x_{2}^{*}\right)+O\left(\delta w \frac{u_{2}^{\prime *}}{c_{0}}, \frac{\delta w}{\omega^{0}}\right)  \tag{3.15}\\
\frac{\partial u_{2}^{\prime}}{\partial u_{2}^{\prime *}}=\mathrm{e}^{-t / \tau}+O\left(\mathrm{e}^{-t / \tau} \frac{\delta u_{i}}{c_{0} \omega^{0}}\right) \\
\delta w=\frac{1}{2}\left(\frac{\delta s}{b^{-}}-\frac{\delta r}{b^{+}}\right), \omega^{0}=k c_{0} \tau
\end{gather*}
$$

As follows from (3.1), in order to determine $m_{2}$ and $\left\langle u_{2}\right\rangle$ it is necessary to evaluate the integral

$$
\begin{equation*}
\langle\Phi\rangle=\frac{m_{2}^{\alpha}}{m_{2}} \frac{1}{\sqrt{2 \pi \sigma}} \int_{-\infty}^{+\infty} \Phi\left(u_{2}\right) \mathrm{e}^{t / \tau} \mathrm{e}^{-\frac{\left(u_{2}^{\prime *}-\delta u_{2} \sin h x_{2}^{*}\right)^{2}}{2 \sigma}} d u_{2} \tag{3.16}
\end{equation*}
$$

Substituting (3.13) and (3.15) into (3.16) and changing variables: and using the inequality $\sqrt{\sigma} / \mathrm{c}_{0} \ll 1$, we have $d u_{2}=d u_{2}^{\prime}, d u_{2}^{\prime}=\frac{\partial u_{2}^{\prime}}{\partial u_{2}^{\prime *}} \partial u_{2}^{\prime *}$,

$$
\begin{align*}
\langle\Phi\rangle= & \frac{m_{2}^{\alpha}}{m_{2}} \frac{1}{\sqrt{2 \pi \sigma}} \int_{-\infty}^{+\infty} \Phi\left(u_{2}\right) \mathrm{e}^{-\frac{\left(u_{2}^{\prime *}-\delta u_{2} \sin k x_{2}^{*}\right)^{2}}{2 \sigma}} d u_{2}^{\prime *}  \tag{3.17}\\
& x=x_{2}^{*}+a t+u_{2}^{\prime *} K+\frac{\delta w}{k \tau} K \cos k x_{2}^{*} \tag{3.18}
\end{align*}
$$

Expanding the argument of the exponential about its maximum, which is determined from the equation

$$
\begin{equation*}
y-\delta u_{2} \sin k x_{2}^{*}(y, t, x)=0 \tag{3.19}
\end{equation*}
$$

we find

$$
\begin{equation*}
f=\left(1+\delta u_{2} k K \cos k x_{2}^{*}(y, t, x)\right)^{2}\left(u_{2}^{\prime *}-y\right)^{2} \tag{3.20}
\end{equation*}
$$

where $f$ is the argument of the exponential in (3.17): $f=\left(u_{2} * *-\delta u_{2} \sin k x_{2} *\right)^{2}$. Substituting (3.20) into (3.17) we obtain

$$
\begin{equation*}
m_{2}\langle\Phi\rangle=\sum_{i=1}^{n} \frac{, m_{2}^{\alpha} \Phi\left(y_{i}, x_{2 i}^{*}\right)}{\left|1+\delta u_{2} k K \cos k x_{2}^{*}\left(y_{i}, t, x\right)\right|} \tag{3.21}
\end{equation*}
$$

where $\Phi=1, \Phi=u_{2}$, and $n$ is the number of roots of Eqs. (3.18) and (3.19). Putting $\Phi=$ $1, n=1$ into (3.21) and comparing with the corresponding expression for $m_{2}$ obtained in [2] with the two-fluid model, we find that they are identical.

If $\delta u_{2} k \tau<1$, then $m_{2}$ is finite everywhere in the half-plane $t \geqq 0,-\infty<x<+\infty$ and in the opposite case ( $\delta \mathrm{u}_{2} \mathrm{k} \tau \geqq 1$ ) there exist points where $\mathrm{m}_{2} \rightarrow \infty$. Setting the denominator in (3.21) equal to zero, we find an equation for a curve in the $t, x_{2} *$ plane on which $m_{2}$ is infinite:

$$
\begin{equation*}
1+\delta u_{2} k K \cos k x_{2}^{*}=0 \tag{3.22}
\end{equation*}
$$

Expanding (3.22) we have

$$
\begin{equation*}
x_{2}^{*}=\frac{\pi}{k}+\frac{2 \pi m}{k} \pm \frac{1}{k}\left(\arccos \frac{1}{\delta u_{2} k h^{k}}\right), \quad m=0, \pm 1, \ldots \tag{3.23}
\end{equation*}
$$

Substituting (3.23) into (3.18), we can write

$$
\begin{equation*}
x=\frac{\pi}{k}+\frac{2 \pi m}{k} \pm \frac{1}{k}\left(\arccos \frac{1}{\delta u_{2} k K}-\sqrt{\left(\delta u_{2} k K\right)^{2}-1}\right)-\delta w /\left(\delta u_{2} k^{2} \tau\right)+a t \quad\left(t>-\tau \ln \left(1-1 /\left(\delta u_{2} k \tau\right)\right)\right) \tag{3.24}
\end{equation*}
$$

Using (3.17), (3.18), and (3.22), we find that on the curve defined by (3.24) to within terms of order $O(\delta w)$ we have the identity $\partial x / \partial x_{2} *=0$; these curves are called caustics [7]. The distribution of trajectories (dashed curves) and caustics (solid curves) are shown for this case in Fig. 4, where $t^{+}=-\tau \ln \left(1-1 / \delta u_{2} k \tau\right)$. The calculation of $m_{2}$ on the caustics is carried out by expanding $f$ up to terms of the fourth power $\left(u_{2}{ }^{\prime} *-y\right)^{4}$ :

$$
f \approx \frac{1}{4}(k K)^{2}\left(\left(\delta u_{2} k K\right)^{2}-1\right)\left(u_{2}^{\prime *}-y\right)^{4}
$$

and substituting the result into (3.17). We thereby find $m_{2}$ on a caustic in the form

$$
\begin{equation*}
m_{2} \approx \frac{2 m_{2}^{\alpha} \Gamma\left(\frac{1}{4}\right)}{\sqrt{2 \pi \sigma^{1 / 4}\left(2(k K)^{2}\left(\left(\delta u_{2} k K\right)^{2}-1\right)\right)^{1 / 4}}} \tag{3.25}
\end{equation*}
$$

where $\Gamma$ is the gamma function. This formula is valid everywhere on the caustic except the point $O^{\prime}$ (and its neighborhood). At the point $O^{\prime}$ we have the expansion $f \approx(1 / 36)\left(\delta u_{2}(k K)^{3}\right)^{2}$. $\left(u_{2}{ }^{\prime} *-y\right)^{6}$ and, therefore, $m_{2}$ is given by the formula

$$
\begin{equation*}
m_{2} \approx \frac{m_{2}^{\alpha}}{3 \sigma^{1 / 3}} \sqrt{\frac{2}{\pi}} \Gamma\left(\frac{1}{6}\right) /\left(K k\left(\delta u_{2}\right)^{1 / 3}\right) \tag{3.26}
\end{equation*}
$$

The applicability condition of (3.26) has the form

$$
m_{2}^{\prime} \ll 1, k d / m_{2}^{\prime} \gg 1, k d<1
$$

where $\mathrm{m}_{2}{ }^{\prime} \approx \mathrm{m}_{2}{ }^{0}\left(\delta \mathrm{u}_{2}{ }^{2} / \sigma\right)^{1 / 3} ; \sigma / \delta \mathrm{u}_{2}{ }^{2}<1 ; \mathrm{m}_{2}{ }^{0} \ll 1$.
Therefore, we have shown that in the continuum-discrete model, without taking into account the volume of the particles, a small perturbation arising at $t=0$ on $-\infty<x<+\infty$ remains finite everywhere in the half-plane $t>0,-\infty<x<+\infty$. The maximum amplitude of the perturbation occurs on the caustics defined by (3.24) and it is inversely proportional to the width of the distribution function raised to a fractional power [Eqs. (3.25) and (3.26)], whereas in the two-fluid model (also without taking into account the volume of the particles) a small perturbation diverges on the caustics according to the law (3.21).

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## CALCULATION OF THE NONEQUILIBRIUM PARAMETERS OF AIR

at The surfaces of models and in the wakes behind them
FOR THE CONDITIONS OF AEROBALLISTIC EXPERIMENTS
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The calculation of the nonequilibrium, quasi-one-dimensional flow of chemically reactive gas mixtures is of practical interest in connection with the study of relaxation processes, obtaining gasdynamic jets for physical measurements, and the investigation of plasma supersonic phenomena in the wake behind a body, etc.

Calculations of chemically nonequilibrium, supersonic, quasi-one-dimensional flows are presented in [1-8] and elsewhere. Here various algorithms are used to solve such problems for flows in nozzles and stream tubes near a body. At present the fields of nonequilibrium parameters at the surfaces of spherically blunted cones are calculated for certain conditions of streamline flow using stream tubes, while calculated results for inviscid flow in wakes are absent. In expansion behind the stern cut of a body, where the gas temperature is sharply reduced, it is necessary to make additional allowance for important reactions with the participation of electrons, negative ions, and polyatomic molecules. Calculations of nonequilibrium parameters in the flow over bodies with surfaces of other shapes, in a wide range of variation of the initial parameters, are also necessary for the comparison and treatment of the results of aeroballistic experiments. However, the absence of calculation methods that are convenient and rapid for execution on computers has prevented making such comparative investigations and giving practical recommendations up to now.

The problem of the flow of a chemically nonequilibrium, partially ionized, multicomponent, inviscid gas from a spherical supersonic source was studied in detail in [9]; from the calculations it is seen that in a number of important cases one can use a constant value of the effective adiabatic index, making it possible to obtain a one-to-one connection between the area of a stream tube and the gas pressure.

In the present paper we give a single algorithm for the computer calculation of the direct and inverse quasi-one-dimensional problems of the flow of chemically nonequilibrium, multicomponent air. The formulation and ways of solving a number of problems of nonequilibrium aerodynamics are discussed on the basis of the calculation method developed.

1. Let us consider the steady quasi-one-dimensional flow of a chemically nonequilibrium gas. The system of dimensionless equations describing such flow has the form [1]

$$
\begin{equation*}
\rho v S(x)=1, \quad \rho v \frac{d v}{d x}=-\frac{d p}{d x} \tag{1.1}
\end{equation*}
$$

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